# What functions can GNNs compute on random graphs? The role of Positional Encodings

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## I - Summary

On large random graphs, GNNs *converge* to prediction functions on some latent space to label nodes. But:

1. the approximation power of these function spaces, and 2. the role of input node features,

are not well-understood.

In this paper, we fully characterize the function space that GNNs can approximate. We study the role of input node features, and in particular of augmenting them with **Positional Encodings**.

- **Approximation theorem** is natural but not trivial: novel result for **ReLU-MLP** universality in  $L^2$  norm.
- Novel concentration result for ReLU-filtered random graphs of independent interest.

# II - Settings and Notations

Latent Space Random Graphs

 $x_i \stackrel{iid}{\sim} P \in \mathcal{P}(\mathbb{R}^p), a_{ij} \sim \text{Bernoulli}(\alpha_n w(x_i, x_j)) \quad 1 \leq i < j \leq n$ 

- ► distribution P with compact support, continuous connectivity kernel w, sparsity factor  $\alpha_n \gtrsim \log n/n$
- **Graph matrix**  $S \in \mathbb{R}^{n \times n}$ , assumed to converge to graph operator S.
  - **Ex 1**: normalized adjacency matrix  $S = A/(n\alpha_n)$ , operator  $Sf(x) = \int w(x, z)f(z)dP(z)$
  - **Ex 2**: normalized Laplacian  $S = D_A^{-\frac{1}{2}}AD_A^{-\frac{1}{2}}$ , operator  $\mathbf{S}f(x) = \int \frac{w(x,z)}{\sqrt{d(x)d(z)}}f(z)dP(z)$

**Assumption**: denoting  $\iota_X f = [f(x_i)]_{i=1}^n$ ,

$$^{-1} \| S\iota_X f - \iota_X \mathbf{S} f \|_F^2 \xrightarrow[n \to \infty]{\mathbb{P}} 0$$

**Prop**: True for the two examples above.

The theory yields normalization strategies for PEs to be consistent across graph sizes, which improves results in practice.

#### **III - Function approximation**

It has been shown [1] that the output of GNNs on large random graphs is close to a prediction function on the latent variables. How can we characterize precisely the functions well-approximated by GNNs?

**Definition**: Given a **base space**  $\mathcal{B}$  of input functions, the set of functions well**approximated** by GNNs is:

$$\mathcal{F}_{\mathsf{GNN}}(\mathcal{B}) = \left\{ f \mid \forall \epsilon, \exists \theta, \exists f^{(0)} \in \mathcal{B}, \ \mathbb{P}\left(n^{-1} \| \Phi_{\theta}(S, \iota_X f^{(0)}) - \iota_X f \|_F^2 \ge \epsilon \right) \to 0 \right\}$$

•  $\theta$  depends on  $\epsilon$ ! This is an **approximation** notion (**not** simply convergence)

▶ What can a GNN do? Structurally, two things: apply *S* (which converges to **S**), and compute MLPs (which can approximate any function).

**Definition**: the **S**-extension  $\mathcal{F}_{\mathbf{S}}(\mathcal{B})$  of  $\mathcal{B}$  is defined by the following rules: 4.  $\mathcal{F}_{\mathbf{S}}(\mathcal{B})$  is a vector space 1.  $\mathcal{B} \subset \mathcal{F}_{\mathbf{S}}(\mathcal{B})$ **?**  $\forall f \in \mathfrak{F}_{c}(\mathfrak{B})$   $\mathsf{S}_{f} \in \mathfrak{F}_{c}(\mathfrak{B})$ 5  $\mathcal{F}_{\mathbf{c}}(\mathcal{B})$  is closed

• **Graph Neural Networks** for node prediction, using *S* and **ReLU**:  

$$Z^{(\ell+1)} = \operatorname{ReLU}\left(Z^{(\ell)}\theta_0^{(\ell)} + SZ^{(\ell)}\theta_1^{(\ell)} + 1_n(b^{(\ell)})^{\top}\right), \quad \Phi_{\theta}(S, Z^{(0)}) = Z^{(L)}\theta^{(L)} + 1_n(b^{(L)})^{\top}$$

# IV - Consequences and input $\mathcal{B}$

We need only focus on  $\mathcal{F}_{\mathbf{S}}(\mathcal{B})$  to characterize the functions computed by GNNs. The inputs to the GNNs  $\mathcal{B}$  is key.

## **Node features** 1. if $Z^{(0)} = \iota_X f^{(0)}$ , then $\mathcal{B} = \{f^{(0)}\}$ 2a. if $Z^{(0)} = \iota_X f^{(0)} + \nu$ with $\nu_i$ centered i.i.d., the noise doesn't vanish (imperfect approximation). 2b. but (e.g.) $Z^{(0)} = S(\iota_X f^{(0)} + \xi)$ restores $\mathcal{B} = \{Sf^{(0)}\}$

#### No node features?

1. Constant  $Z^{(0)} = 1_n$  yields  $\mathcal{B} = \{1\}$ 2. Degrees  $Z^{(0)} = S1_n$  yields  $\mathcal{B} = \{\mathbf{S}1\}$ , but same  $\mathcal{F}_{\mathbf{S}}(\mathcal{B})$ 3. More recently, "Positional Encodings" (PE) [2]:

$\mathbf{Z} \cdot \mathbf{V} \in J \mathbf{S}(\mathcal{D}),  \mathbf{J} \in J \mathbf{S}(\mathcal{D})$	<b>J.</b> $JS(D)$ is closed
<b>3.</b> $\forall f \in \mathcal{F}_{\mathbf{S}}(\mathcal{B}), g \text{ Lip., } g \circ f \in \mathcal{F}_{\mathbf{S}}(\mathcal{B})$	6. $\mathcal{F}_{\mathbf{S}}(\mathcal{B})$ is minimal

Thm.

 $\mathcal{F}_{\mathsf{GNN}}(\mathcal{B}) = \mathcal{F}_{\mathsf{S}}(\mathcal{B})$ 

I he result is natural, the proof not so trivial!

test error=0.018

- Need to prove *both* sides of the inclusion
- $\blacktriangleright$  L<sup>2</sup> norm (convergence of GNNs) and L<sup>\infty</sup> norm (universality of MLPs) do not mix well: need **new**, **specialized universality** theorem for ReLU MLPs in  $L^2$

test error=0.565

 $Z^{(0)} = \mathsf{PE}_{\nu}(S, Z)$ 

- $\blacktriangleright$  potentially considering existing node features Z (often simple) concatenation)
- Ex: Spectral, random walk... need to be **permutation** equivariant  $PE_{\gamma}(\pi S\pi^{\top}, \pi Z) = \pi PE_{\gamma}(S, Z)$

# V - Spectral PEs and SignNet

Take  $u_1^S$ ,  $u_2^S$ ... the eigenvectors of S by decreasing eigenvalues. SignNet [2] is a type of spectral-PEs insensitive to sign ambiguity:

$$\mathsf{PE}_{\gamma}(S) = \left[\mathsf{MLP}_{\gamma_i}(\sqrt{n}u_i^S) + \mathsf{MLP}_{\gamma_i}(-\sqrt{n}u_i^S)\right]_{i=1}^q \in \mathbb{R}^{n \times q}$$

It is known that eigenvectors often converge to the **eigenfunctions**  $u_i^{\mathbf{S}}$  of **S**:

**Thm**: for a p.s.d. kernel w or SBM random graphs, SignNet yields  $\mathcal{B}_{\mathsf{PE}} = \left\{ [f_i \circ u_i^{\mathsf{S}} + f_i \circ (-u_i^{\mathsf{S}})]_{i=1}^q \mid f_i \text{ continuous} \right\}$ 

w psd or SBM for simplicity (not necessary, case-by-case basis) **•** normalization  $\sqrt{n}$  necessary since  $||u_i^S|| = 1$  in  $\mathbb{R}^n$ .

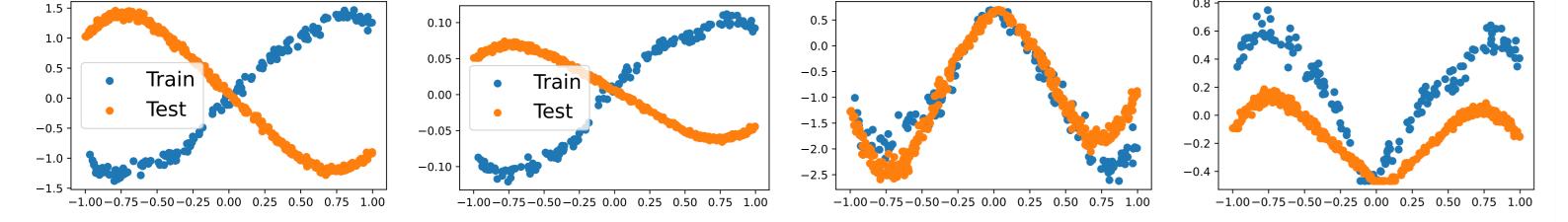
Distance-encoding PEs [2] aggregate distances (random walk, shortest path, etc.). Many choices, here we take the **columns of**  $S^k$  **aggregated with DeepSet** (aka MLP + average):

 $\mathsf{PE}_{\gamma}(S) = n^{-1} \sum_{j} \mathsf{MLP}_{\gamma}(n [Se_j, \dots, S^q e_j]) \in \mathbb{R}^{n \times q}$ This does **not** converge! We need to use a **ReLU**-**MLP filter** on the eigenvalues of  $S \leftarrow S_{\xi} = h_{\text{MLP}_{\xi}}(S)$ and a novel concentration result for ReLU-filtered random graphs (of independent interest).

**VI** - **Distance-encoding PEs** 

0.15 - No filter • Learned filt 0.10 0.15

**Thm**: for a p.s.d. kernel w or SBM random graphs, with  $S = S_{\xi}$  above,



Left to right: before SignNet with normalization, without normalization, after SignNet idem.

distance-PE yields (with 
$$\delta_x$$
 "Dirac" at  $x$ )  

$$\mathcal{B}_{\mathsf{PE}} = \left\{ \int f\left( [\mathbf{S} \delta_x, \dots, \mathbf{S}^q \delta_x] \right) dP(x) \mid f : \mathbb{R}^q \to \mathbb{R}^p \right\}$$

$$\blacktriangleright \mathcal{F}_{\mathbf{S}}(\mathcal{B}_{\mathsf{PE}}) \text{ is then sometimes universal! Generalization of [4]}$$

## **VII** - Other properties

**Prop.** GNNs are useful: for all examples, there are cases where  $\mathcal{B}_{PE} \subset \mathcal{F}_{\mathbf{S}}(\mathcal{B}_{PE})$  strictly **Prop. PEs are powerful**: for all examples, there are cases where  $\mathcal{F}_{\mathbf{S}}(\{1\}) \subset \mathcal{F}_{\mathbf{S}}(\mathcal{B}_{\mathsf{PE}})$  strictly

Dataset	Eigenvectors		Distance-encoding	
	w/ norm.	w/o norm.	w/ norm.	w/o norm.
Synthetic	68.61	65.59	67.31	62.49
<pre>Synthetic (out-of-dist)</pre>	67.87	62.51	66.80	63.33
CiteSeer-subgraphs	49.45	49.43	48.99	37.09
IMDB-BINARY (graph-classif.)	67.80	66.10	71.10	63.95
COLLAB (graph-classif.)	73.74	74.77	75.65	75.02

[1] Keriven, Bietti, Vaiter. Convergence and Stability of Graph Convolutional Networks on Large Random Graphs, NeurIPS 2020.

Dwivedi et al. Graph Neural Networks with Learnable Structural and **Positional Representations**, *ICLR* 2022.

[3] Lim et al. Sign and Basis Invariant Networks for Spectral Graph **Representation Learning**, *ICLR* 2022.

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